

Algorithme de Changement d'Ordre de Complexité Sous-Cubique

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Motivation: zero-dim PoSSo and applications

PoSSo: Polynomial System Solving

PoSSo Problem: univariate polynomial representation

Input: $\mathcal{I} = \langle f_1, \dots, f_s \rangle \subset \mathbb{K}[x_1, \dots, x_n]$

Assumptions: \mathcal{I} radical and zero-dimensional, \mathbb{K} infinite

Output: $\mathcal{I} = \langle x_1 - h_1(x_n), \dots, x_{n-1} - h_{n-1}(x_n), h_n(x_n) \rangle$.

Applications

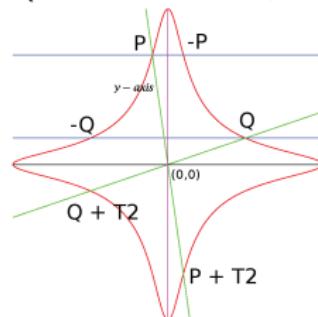
Coding theory, cryptanalysis, computational game theory, optimization, etc

Example: Point Decomposition Problem (DLP over Elliptic Curves)

$$R = P_1 \oplus \cdots \oplus P_n$$

$$P_i \in \mathcal{F}$$

Faugère, Gaudry, Huot, R. (J. Crypto 13)



State of the art

D = degree of $\mathcal{I} \subset \mathbb{K}[x_1, \dots, x_n] = \#\text{solutions of } f_1 = \dots = f_s = 0.$

Particular cases

\mathbb{K} field of characteristic zero; $\delta \leq D$ number of real roots.

- (Mourrain, Pan 1998) Approximate all the real roots: $\tilde{O}(12^n D^2)$ if $\delta = O(\log_2(D))$;
- (Bostan, Salvy, Schost 2003) RUR: $\tilde{O}(n2^n D^{\frac{5}{2}})$ if the multiplicative structure of the quotient ring is known.

General case

Computing **Univariate Polynomial Representation**: $O(nD^3)$.

Our aim

The **first algorithm** with **sub-cubic complexity** to solve this problem.

PoSSo and Gröbner basis

- Efficient Computation of 0-dim Gröbner Bases by Change of Ordering
(FGLM: Faugère, Gianni, Lazard, Mora 1993)

Univ. Pol. Representation \simeq LEX Gröbner basis in *Shape position*.

Efficient Computation of a LEX Gröbner basis

Input: $S \subset \mathbb{K}[x_1, \dots, x_n]$.

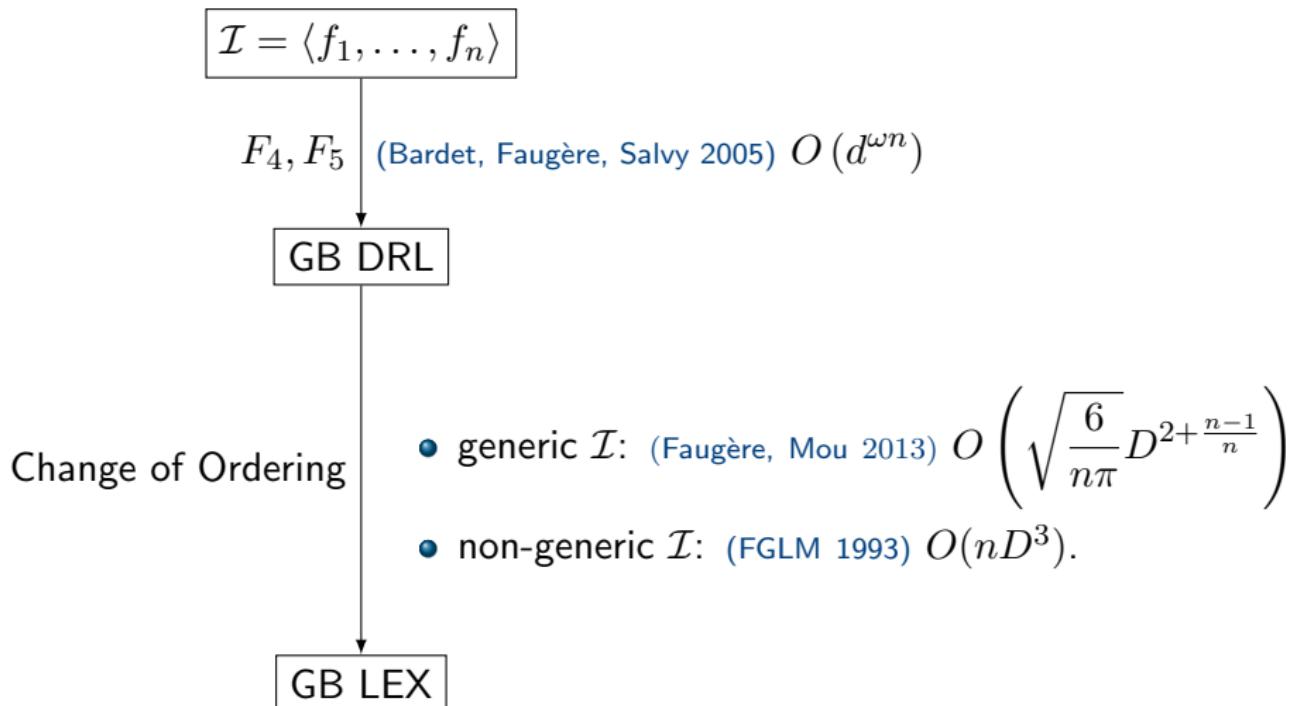
Output: The LEX Gröbner basis of $\langle S \rangle$.

- ① Compute DRL Gröbner basis of $\langle S \rangle$;
- ② Compute LEX Gröbner basis of $\langle S \rangle$ by change of ordering algorithm.

Gröbner basis and Complexity

(f_1, \dots, f_n) regular sequence with $\deg(f_i) \leq d$.

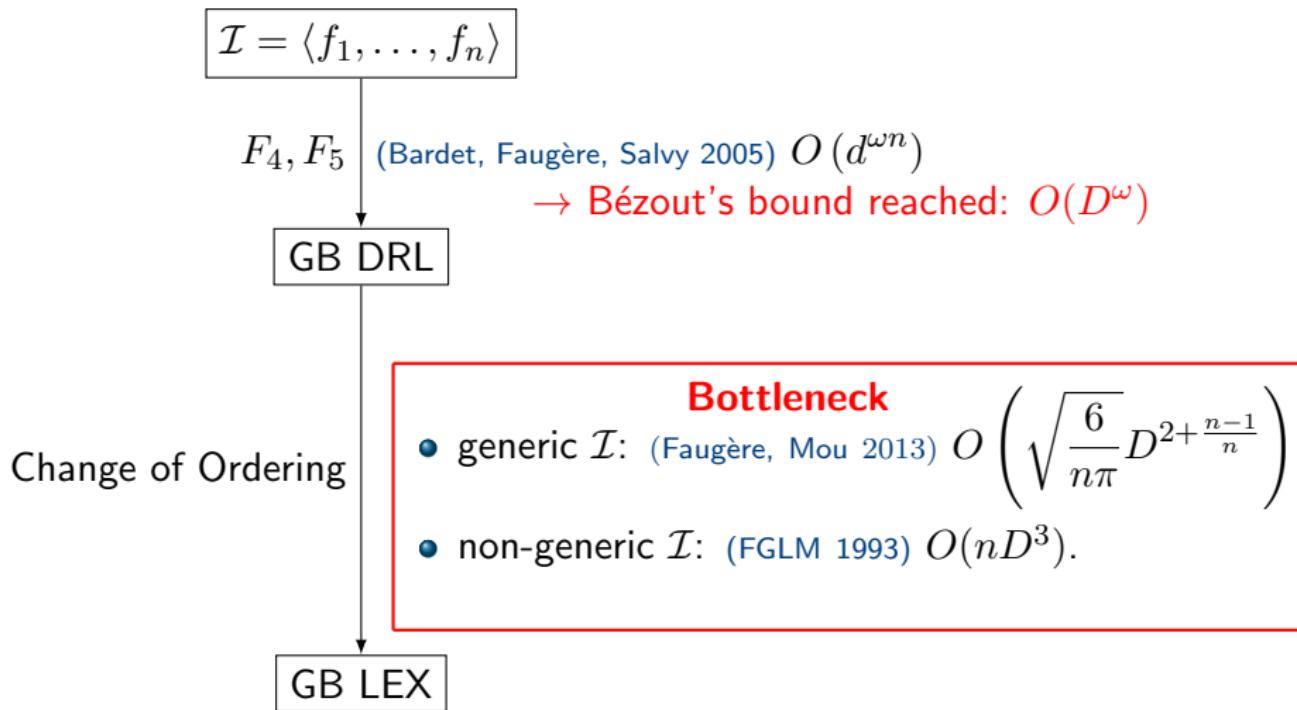
$2 \leq \omega < 2.3727$ is the linear algebra constant.



Gröbner basis and Complexity

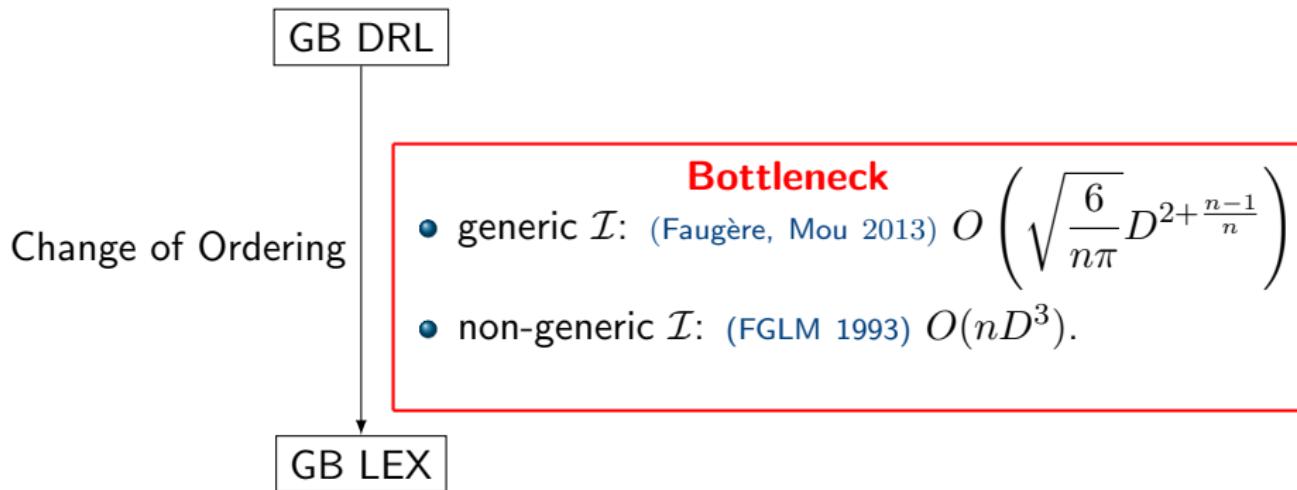
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☞ Change of ordering in $\tilde{O}(nD^\omega) \Rightarrow$ PoSSo in $\tilde{O}(d^{\omega n} + nD^\omega)$

Change of Ordering Complexity: Contributions



☞ Change of ordering in $\tilde{O}(nD^\omega) \Rightarrow$ PoSSo in $\tilde{O}(d^{\omega n} + nD^\omega)$

Contributions

- Consideration of Faugère & Mou in the non sparse case
- Use of the staircases structures for LEX and DRL Gröbner basis

Gröbner basis

Initial ideal

\mathcal{I} an ideal and $>$ a monomial ordering $\text{in}_>(\mathcal{I}) = \{\text{LT}_>(f) \mid f \in \mathcal{I}\}$.

Gröbner basis (not unique)

Fix a monomial ordering $>$, $\{g_1, \dots, g_s\}$ GB w.r.t. $>$ of \mathcal{I} if

- $\{g_1, \dots, g_s\} \subset \mathcal{I}$;
- $\langle \text{LT}_>(g_1), \dots, \text{LT}_>(g_s) \rangle = \text{in}_>(\mathcal{I})$.

Reduced Gröbner basis (unique)

$G = \{g_1, \dots, g_s\}$ GB of $\mathcal{I} \subset \mathbb{K}[x_1, \dots, x_n]$ w.r.t. $>$ s.t.

$\text{LT}_>(g_i)$ does not divide any terms in g_j for all $1 \leq i \neq j \leq s$.

$\Rightarrow g_i = \text{LT}_>(g_i) + \sum_{\alpha \in \mathbb{N}^n} c_\alpha x^\alpha$ with $x^\alpha \notin \text{in}_>(\mathcal{I})$.

Quotient ring

Normal Form

Let $\mathcal{I} \subset \mathbb{K}[x_1, \dots, x_n]$ be an ideal. For any $f \in \mathbb{K}[x_1, \dots, x_n]$ there exists a **unique** $h \in \mathbb{K}[x_1, \dots, x_n]$ s.t.

- $f - h \in \mathcal{I}$;
- $h = \sum_{\alpha \in \mathbb{N}^n} c_\alpha x^\alpha$ with $x^\alpha \notin \text{in}_>(\mathcal{I})$.

$$h = \text{NF}_>(f)$$

Quotient ring as \mathbb{K} -vector space of dimension D

$$\mathbb{K}[x_1, \dots, x_n]/\mathcal{I} = \{[f] \mid f \in \mathcal{I}\} \simeq \text{Span}(x^\alpha \notin \text{in}_>(\mathcal{I}))$$

with $[f] = \{h \in \mathbb{K}[x_1, \dots, x_n] \mid f - h \in \mathcal{I}\}$.

$$\mathcal{I} \text{ dimension zero} \Rightarrow \{x^\alpha \notin \text{in}_>(\mathcal{I})\} = \{\epsilon_D > \dots > \epsilon_1 = 1\}$$

Change of ordering algorithm: key ideas

Coordinate vector ($\mathcal{G}_>$ GB of \mathcal{I} w.r.t. $>$)

$$v_\alpha = (c_1, \dots, c_D) \text{ s.t. } \text{NF}_>(x^\alpha) = \sum_{i=1}^D c_i \epsilon_i.$$

$$\begin{aligned} f = \sum_{\alpha \in \mathbb{N}^n} c_\alpha x^\alpha \in \mathcal{I} &\Leftrightarrow \text{NF}_>(f) = 0 \\ &\Leftrightarrow \sum_{\alpha \in \mathbb{N}^n} c_\alpha v_\alpha = 0 \end{aligned}$$

Multiplication matrices $\mu_{x_1}, \dots, \mu_{x_n}$

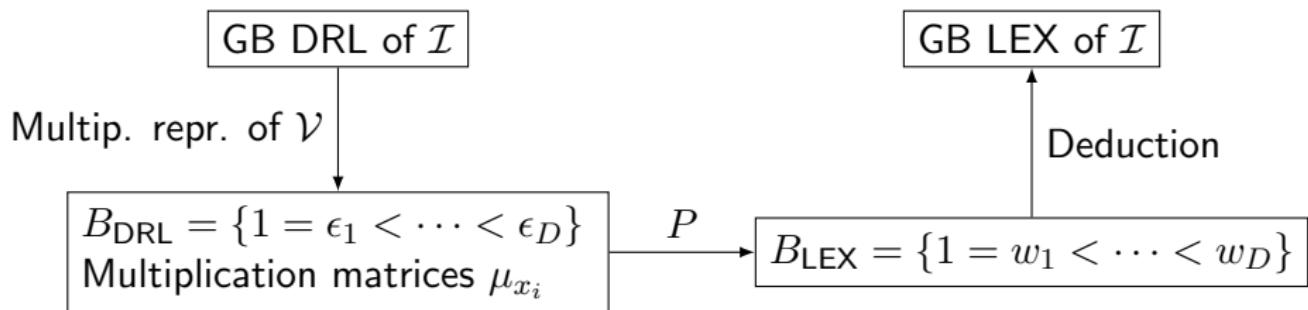
$$\mu_{x_i} = \begin{pmatrix} \text{NF}_>(\epsilon_1 x_i) & \cdots & \text{NF}_>(\epsilon_D x_i) \\ \star & \cdots & \star \\ \vdots & \ddots & \vdots \\ \star & \cdots & \star \end{pmatrix} \begin{matrix} \epsilon_1 \\ \vdots \\ \epsilon_D \end{matrix}$$

Let $\mathbf{1} = (1, 0, \dots, 0) = v_{(0, \dots, 0)} \rightsquigarrow v_\alpha = \mu_{x_1}^{\alpha_1} \cdots \mu_{x_n}^{\alpha_n} \mathbf{1}$

FGLM in a nutshell

From DRL to LEX with $x_1 > x_2 > \dots > x_n$

$\mathcal{V} = \mathbb{K}[x_1, \dots, x_n]/\mathcal{I}$ is a D -dim \mathbb{K} -vector space

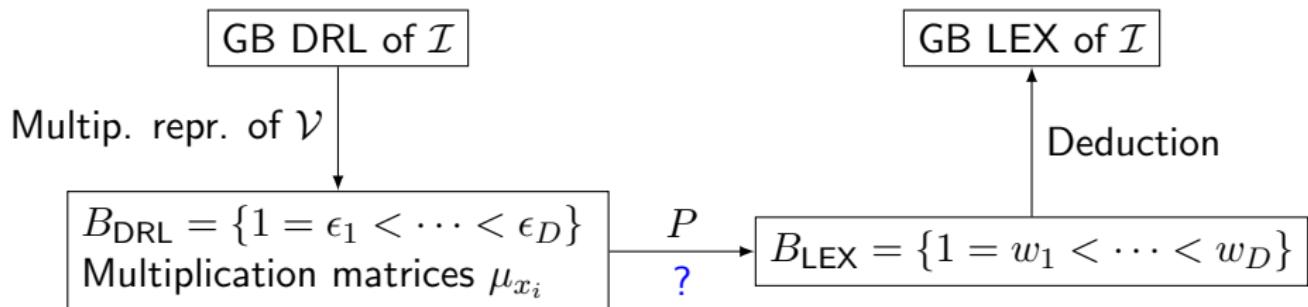


- $B_{\text{DRL}} = P \cdot B_{\text{LEX}}$
- $\mu_{x_i} : t \rightarrow \text{NF}_{\text{DRL}}(x_i t)$

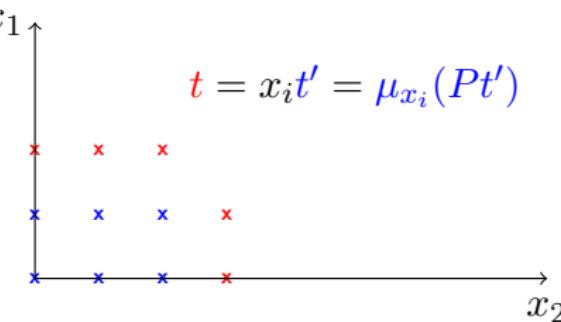
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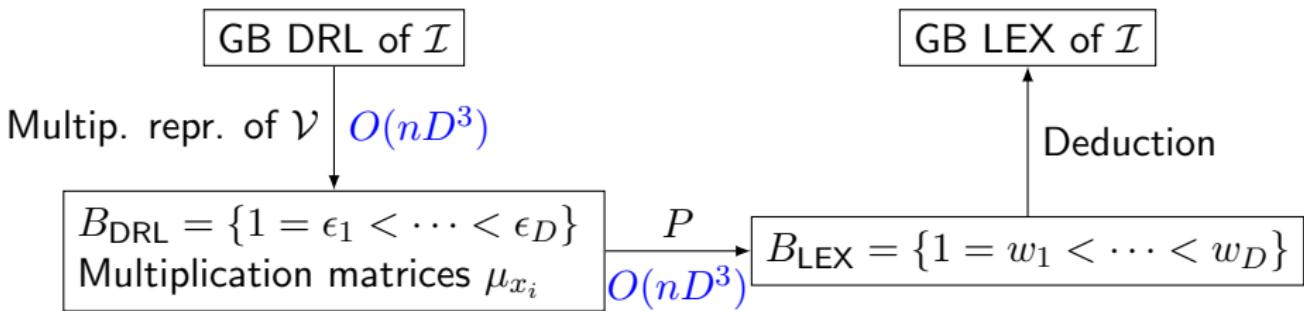
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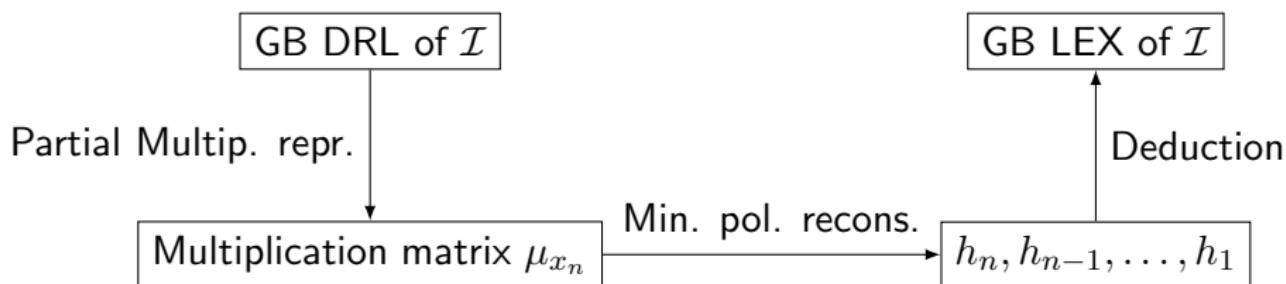
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☞ Use structures of GB LEX

Faugère & Mou Sparse FGLM framework

Assumption: GB LEX of \mathcal{I} is in *shape position*

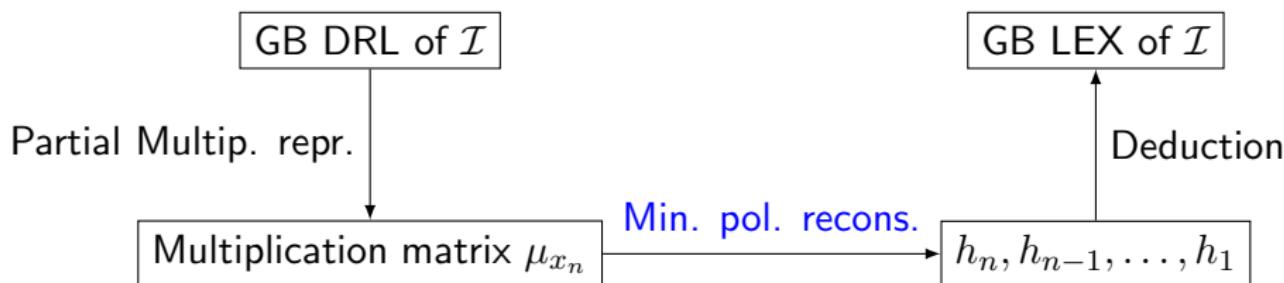
$$\mathcal{I} = \langle x_1 - h_1(x_n), \dots, x_{n-1} - h_{n-1}(x_n), h_n(x_n) \rangle$$



Faugère & Mou Sparse FGLM framework

Assumption: GB LEX of \mathcal{I} is in *shape position*

$$\mathcal{I} = \langle x_1 - h_1(x_n), \dots, x_{n-1} - h_{n-1}(x_n), \textcolor{blue}{h_n(x_n)} \rangle$$



Faugère & Mou reconstruction of h_i : deterministic Wiedemann

- $\mu_{x_n}^j \cdot \mathbf{1}, \mu_{x_n}^j(\mu_{x_1} \cdot \mathbf{1}), \dots, \mu_{x_n}^j(\mu_{x_{n-1}} \cdot \mathbf{1}), j \in \{0, \dots, 2D - 1\}$
- n Hankel linear systems to solve $\tilde{O}(nD^2)$

Faugère & Mou Sparse FGLM framework

$h_n : S = [(\mathbf{r}, \mu_{x_n}^j \mathbf{1}) \mid j = 0, \dots, 2D - 1]$ with $(\mathbf{r}, \mu_{x_n}^j \mathbf{1}) = (^t \mu_{x_n}^j \mathbf{r}, \mathbf{1})$

Compute h_1, \dots, h_{n-1}

$$h_i(x_n) = \sum_{k=0}^{D-1} c_{i,k} x_n^k$$

$$x_i - h_i(x_n) \in \mathcal{I} \Leftrightarrow \mu_{x_i} \mathbf{1} - \sum_{k=0}^{D-1} c_{i,k} \mu_{x_n}^k \mathbf{1} = \mathbf{0}$$

$\times \mu_{x_n}^j$ for $j = 0, \dots, D - 1$ and $(r, \cdot) \rightsquigarrow$ **Hankel** linear systems

$$\underbrace{\begin{pmatrix} (^t \mu_{x_n}^0 \mathbf{r}, \mu_{x_i} \mathbf{1}) \\ (^t \mu_{x_n}^1 \mathbf{r}, \mu_{x_i} \mathbf{1}) \\ \vdots \\ (^t \mu_{x_n}^{D-1} \mathbf{r}, \mu_{x_i} \mathbf{1}) \end{pmatrix}}_{\mathbf{b}_i} = \underbrace{\begin{pmatrix} (^t \mu_{x_n}^0 \mathbf{r}, \mathbf{1}) & (^t \mu_{x_n}^1 \mathbf{r}, \mathbf{1}) & \dots & (^t \mu_{x_n}^{D-1} \mathbf{r}, \mathbf{1}) \\ (^t \mu_{x_n}^1 \mathbf{r}, \mathbf{1}) & (^t \mu_{x_n}^2 \mathbf{r}, \mathbf{1}) & \dots & (^t \mu_{x_n}^D \mathbf{r}, \mathbf{1}) \\ \vdots & \vdots & \ddots & \vdots \\ (^t \mu_{x_n}^{D-1} \mathbf{r}, \mathbf{1}) & (^t \mu_{x_n}^D \mathbf{r}, \mathbf{1}) & \dots & (^t \mu_{x_n}^{2D-2} \mathbf{r}, \mathbf{1}) \end{pmatrix}}_{\mathcal{H}} \underbrace{\begin{pmatrix} c_{i,0} \\ c_{i,1} \\ \vdots \\ c_{i,D-1} \end{pmatrix}}_{\mathbf{c}_i}$$

Faugère & Mou Sparse FGLM framework

Assumption: GB LEX of \mathcal{I} is in *shape position*

$$\mathcal{I} = \langle x_1 - h_1(x_n), \dots, x_{n-1} - h_{n-1}(x_n), \textcolor{blue}{h_n(x_n)} \rangle$$



Faugère & Mou reconstruction of h_i : deterministic Wiedemann μ_{x_n} **dense**

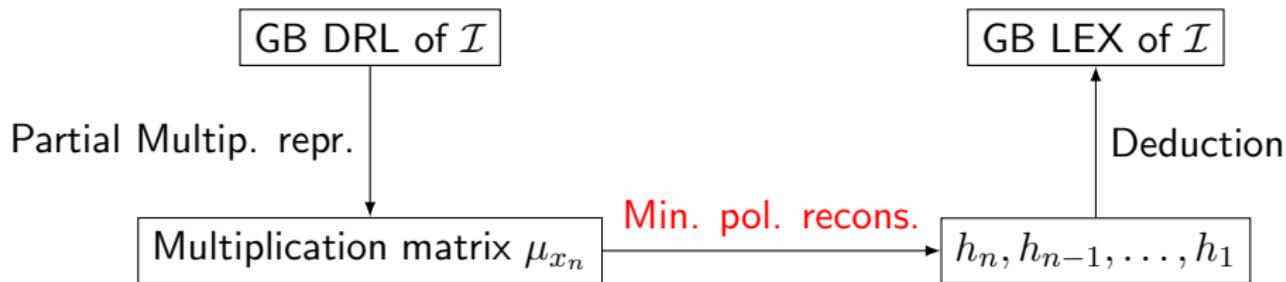
- $\mu_{x_n}^j \cdot \mathbf{1}, \mu_{x_n}^j(\mu_{x_1} \cdot \mathbf{1}), \dots, \mu_{x_n}^j(\mu_{x_{n-1}} \cdot \mathbf{1}), j \in \{0, \dots, 2D-1\}$ $O(nD^3)$
- n Hankel linear systems to solve $\tilde{O}(nD^2)$

☞ $\mu_{x_i} \cdot \mathbf{1} = x_1$ is known with no cost $\Rightarrow \mu_{x_n}$ is sufficient!

Faugère & Mou Sparse FGLM framework

Assumption: GB LEX of \mathcal{I} is in *shape position*

$$\mathcal{I} = \langle x_1 - h_1(x_n), \dots, x_{n-1} - h_{n-1}(x_n), \textcolor{blue}{h_n(x_n)} \rangle$$



Contribution: use of Keller-Gehrig $O(n \log(D) D^\omega)$

$$\mu_{x_n}^2 (\mu_{x_n} \mathbf{r} \mid \mathbf{r}) = (\mu_{x_n}^3 \mathbf{r} \mid \mu_{x_n}^2 \mathbf{r})$$

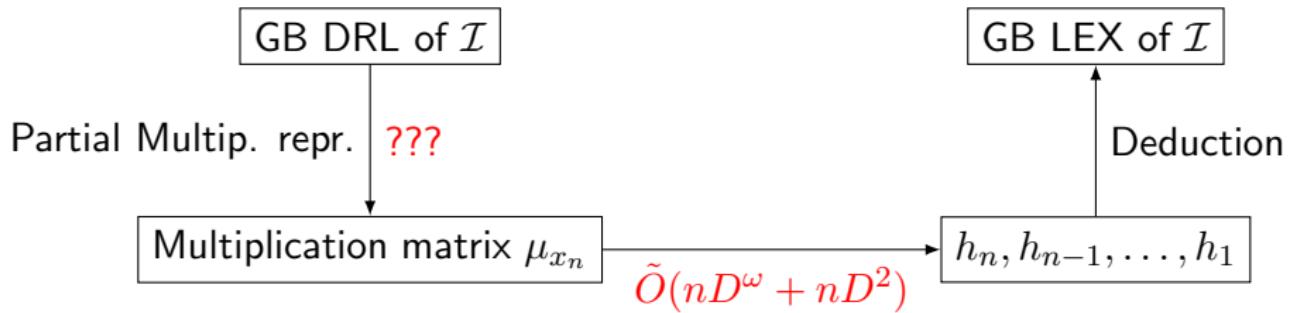
⋮

$$\mu_{x_n}^{2^{\lceil \log_2(D) \rceil}} (\mu_{x_n}^{2^{\lceil \log_2(D) \rceil}-1} \mathbf{r} \mid \dots \mid \mathbf{r}) = (\mu_{x_n}^{2D-1} \mathbf{r} \mid \mu_{x_n}^{2D-2} \mathbf{r} \mid \dots \mid \mu_{x_n}^{2^{\lceil \log_2(D) \rceil}} \mathbf{r})$$

Faugère & Mou Sparse FGLM framework

Assumption: GB LEX of \mathcal{I} is in *shape position*

$$\mathcal{I} = \langle x_1 - h_1(x_n), \dots, x_{n-1} - h_{n-1}(x_n), \textcolor{blue}{h_n(x_n)} \rangle$$



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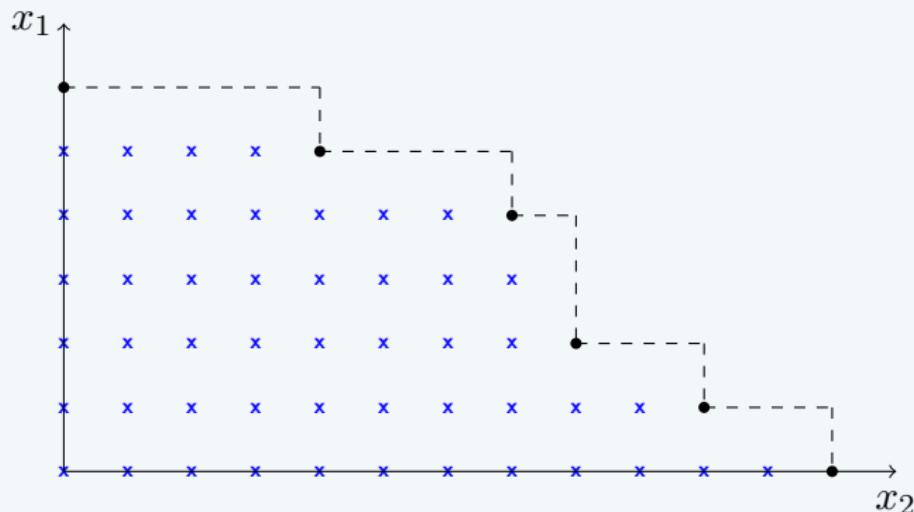
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Computing μ_{x_n} : the FGML Lemma

Computing $\mu_{x_n} \Leftrightarrow$ computing $\text{NF}_{\text{drl}}(\epsilon_i x_n)$ $i \in \{1, \dots, D\}$.

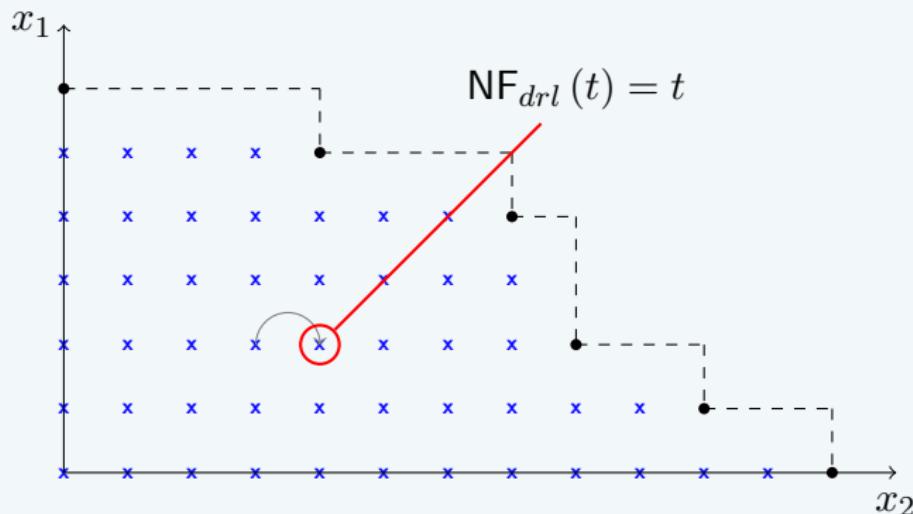
FGML Lemma – Only three cases to consider



Computing μ_{x_n} : the FGLM Lemma

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FGLM Lemma – Only three cases to consider

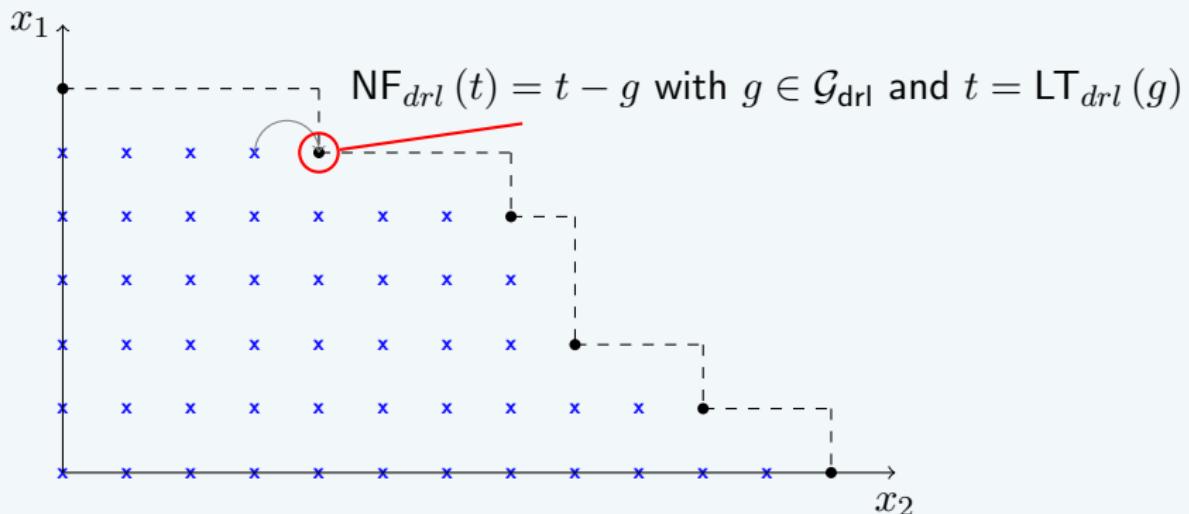


Case (1) $t = \epsilon_i x_j \in B$

Computing μ_{x_n} : the FGML Lemma

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FGML Lemma – Only three cases to consider



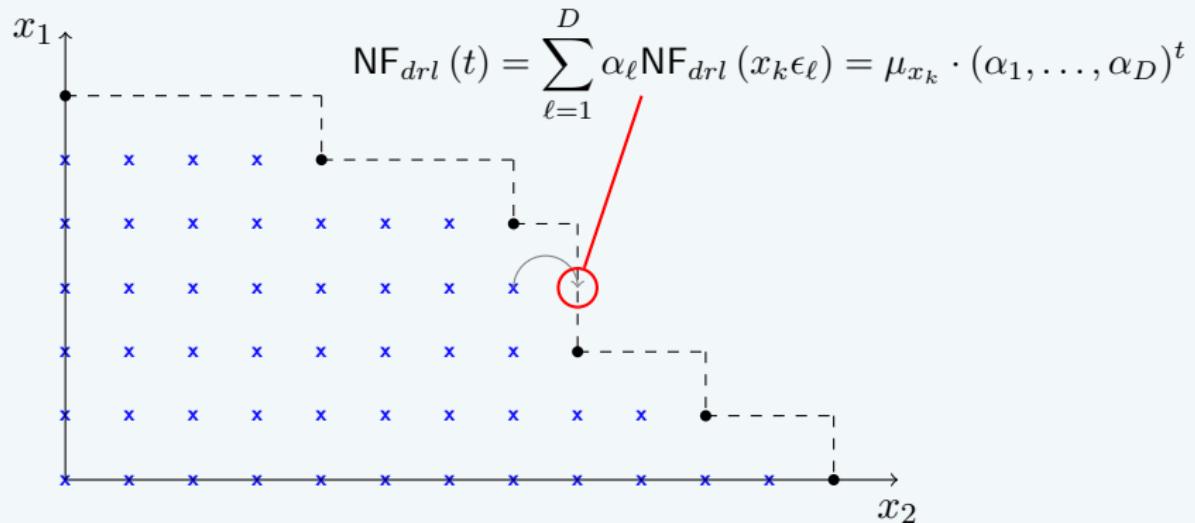
Case (2) $t = \epsilon_i x_j \in E(I) = \{\text{LT}_{\text{drl}}(g) \mid g \in \mathcal{G}_{\text{drl}}\}$

Computing μ_{x_n} : the FGML Lemma

Computing $\mu_{x_n} \Leftrightarrow$ computing $\text{NF}_{\text{drl}}(\epsilon_i x_n)$ $i \in \{1, \dots, D\}$.

$F = \{\epsilon_i x_j \mid i = 1, \dots, D \text{ and } j = 1, \dots, n\} \setminus B$: border

FGML Lemma – Only three cases to consider

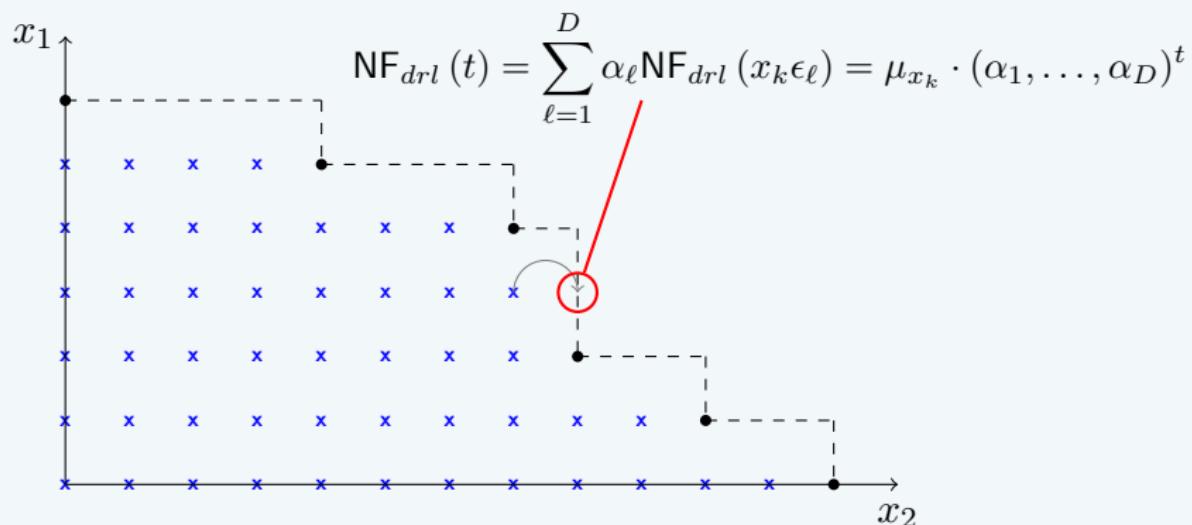


Case (3) $t = \epsilon_i x_i \in F \setminus E(I) \Rightarrow t = x_k t'$ with $t' \in F$ with $\text{NF}_{\text{drl}}(t') = \sum_{i=\ell}^D \alpha_i \epsilon_i$

Computing μ_{x_n} : the FGML Lemma

Computing $\mu_{x_n} \Leftrightarrow$ computing $\text{NF}_{drl}(\epsilon_i x_n)$ $i \in \{1, \dots, D\}$.

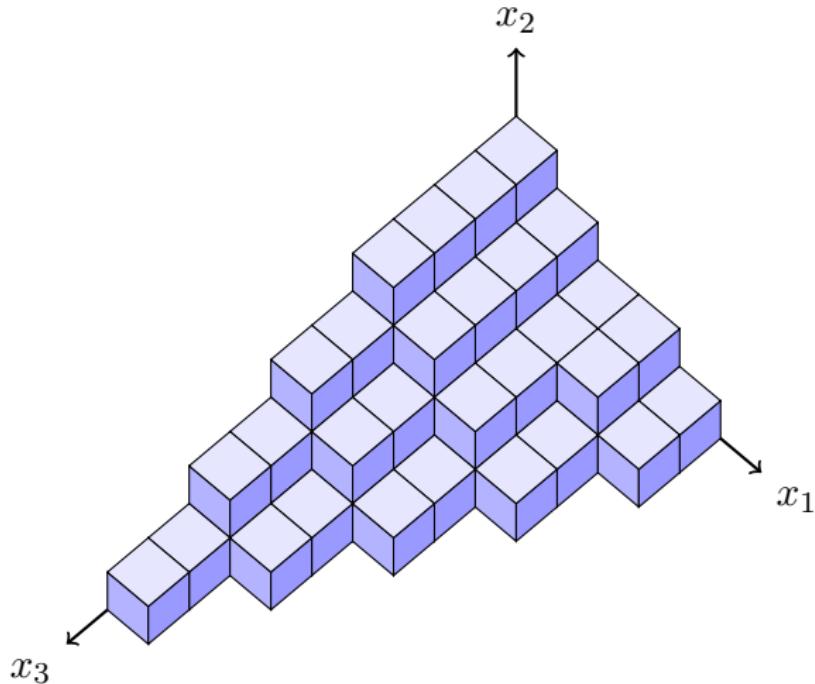
FGML Lemma – Only three cases to consider



☞ Only the Case (3) is costly - can a structure avoid it?

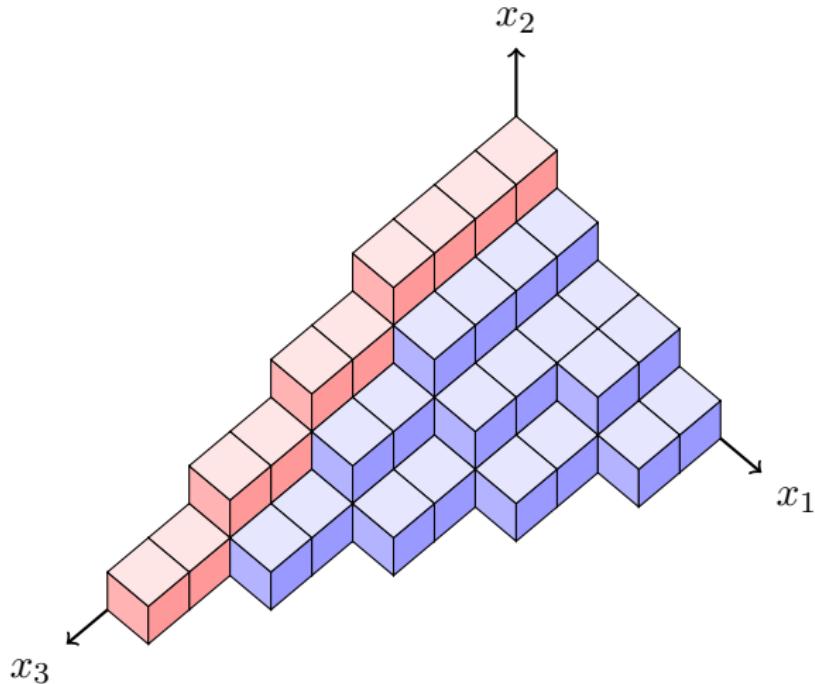
The $(1, 2)$ -staircases position

DRL ordering with $x_1 > x_2 > x_3$



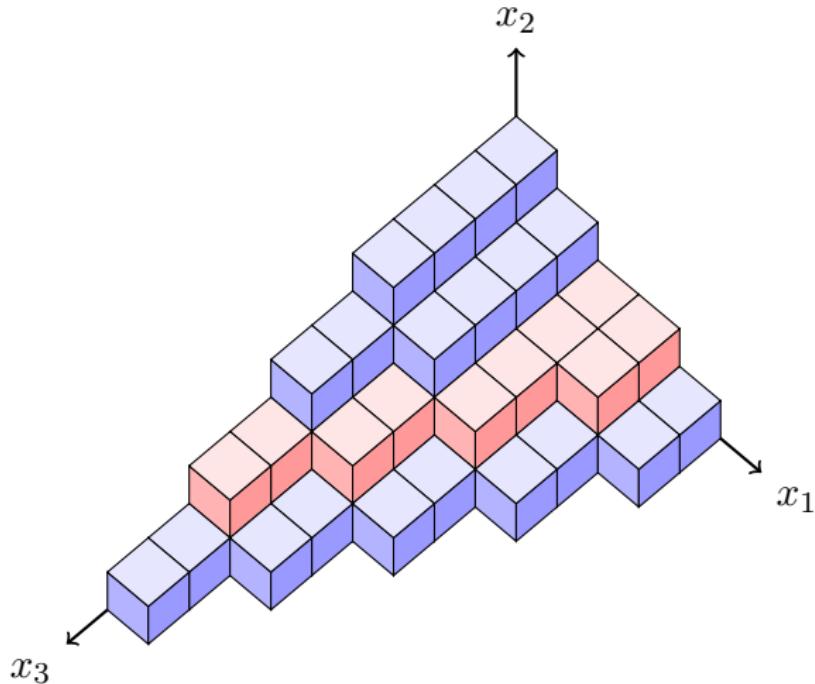
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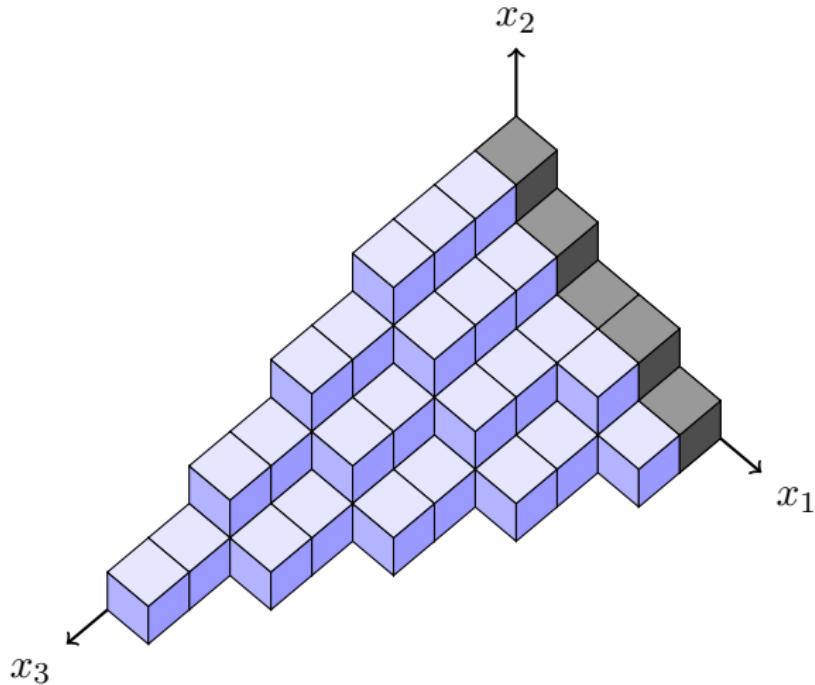
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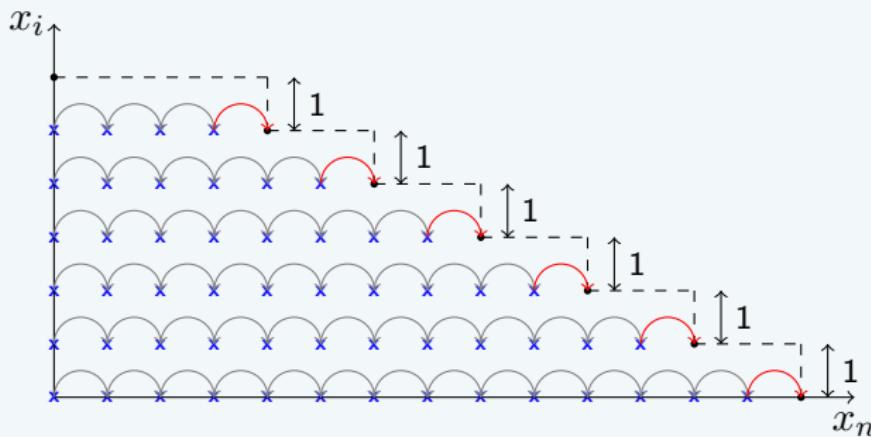
The $(1, 2)$ -staircases position: Generic Ideals

Moreno-Socias 1992

For a generic ideal \mathcal{I} , its DRL GB verifies $\epsilon x_n \in B \cup E(\mathcal{I})$ for $\epsilon \in B$.
A generic ideal is in $(1, 2)$ -staircases position.

FGLM Lemma: the no cost situation

For any instantiation of \deg_{x_j} for $j \in \{1, \dots, n-1\} \setminus \{i\}$

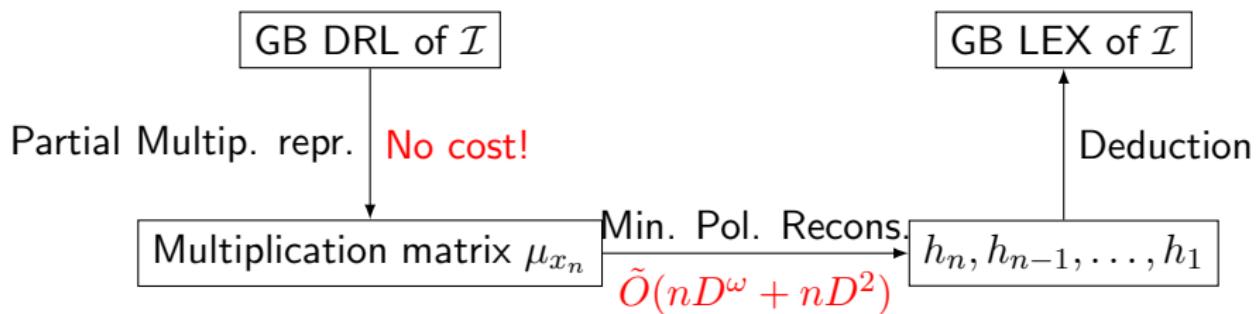


☞ The computation of μ_{x_n} is free!

Faugère & Mou Sparse FGLM framework

Assumptions: LEX GB of \mathcal{I} is in *shape position*

DRL GB of \mathcal{I} is in $(1, 2)$ -staircases position (**Generic Ideals**)



☞ Non generic ideals?

(1, 2)-staircases and shape position

Galligo, Bayer and Stillman, Pardue (1970's - 2000's)

\mathcal{I} an *homogeneous ideal*. There exists a Zariski open subset $U \subset \mathrm{GL}(\mathbb{K}, n)$ s.t. $\forall g \in U$, $g \cdot \mathcal{I}$ is in *(1,2)-staircases position*.

Shape Lemma, Gianni and Mora (1989)

\mathcal{I} a *radical ideal*. There exists a Zariski open subset $U' \subset \mathrm{GL}(\mathbb{K}, n)$ s.t. $\forall g \in U'$, $g \cdot \mathcal{I}$ is in *Shape position*.

Main theorem

☞ The (1, 2)-staircases and shape position is generic!

\mathcal{I} regular affine 0-dim and radical and $g \in U \cap U' (\neq \emptyset)$. The change of ordering from DRL to LEX of $g \cdot \mathcal{I}$ can be done in

$$\tilde{O}(nD^\omega + nD^2)$$

☞ "Randomization" on the choice of g

New algorithm for PoSSo

Let d such that $\deg(f_i) \leq d$.

Algorithm 1: Another algorithm for PoSSo.

Input : $S = \{f_1, \dots, f_n\} \subset \mathbb{K}[x_1, \dots, x_n]$ s.t. $\langle S \rangle$ is radical and regular.

Output: g in $\text{GL}(\mathbb{K}, n)$ and the LEX Gröbner basis of $\langle g \cdot S \rangle$ or *fail*.

“Randomly” choose g in $\text{GL}(\mathbb{K}, n)$;

Compute \mathcal{G}_{drl} the DRL GB $g \cdot S$; O(d^{ωn})

if μ_{x_n} can be read from \mathcal{G}_{drl} **then**

 Extract μ_{x_n} from \mathcal{G}_{drl} ; No cost

if $\langle g \cdot S \rangle$ is in Shape Position **then**

 From μ_{x_n} and \mathcal{G}_{drl} compute

\mathcal{G}_{lex} ; O(log₂(D)(nD^ω + n log₂(D)D²))

return g and \mathcal{G}_{lex} ;

return *fail*;

Total complexity: \tilde{O}(d^{ωn} + nD^ω) arithmetic operations.

Practical implications

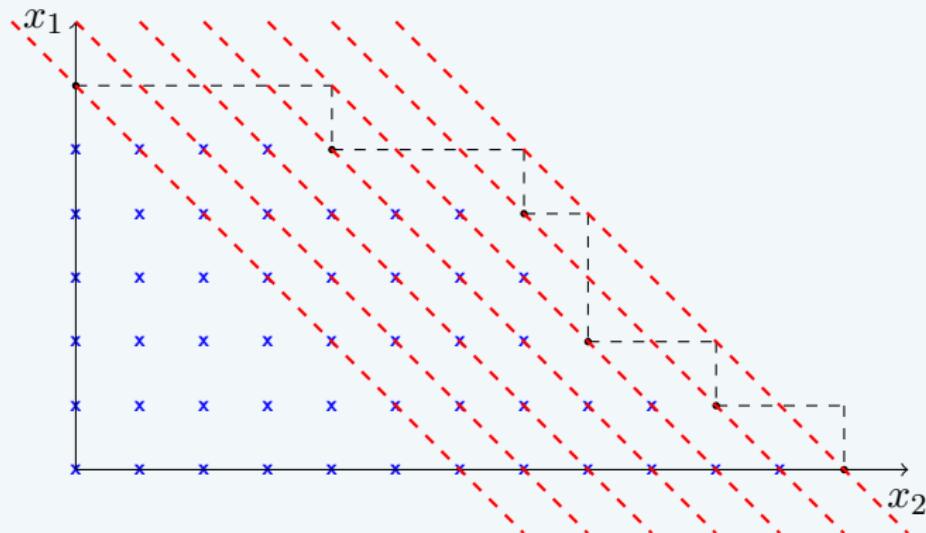
System	n	D	Algorithm	\mathcal{G}_{drl}	μ_{x_n}	#NF	\mathcal{G}_{lex}	Total
Random $d = 2$	15	32 768	usual	1 580s	41.5s	0	1 330s	2 950s
			This work	1 580s	41.5s	0	1 330s	2 950s
Random $d = 6$	6	46 656	usual	632s	20.3s	0	1 700s	2 350s
			This work	632s	20.3s	0	1 700s	2 350s
Random $d = 30$	3	27 000	usual	48.7s	0.9s	0	95.6s	145s
			This work	48.7s	0.9s	0	95.6s	145s
Eco	13	2 048	usual	28.2s	36.5s	1 153	0.43s	65.1s
			This work	12.0s	0.18s	0	0.23s	12.4s
	14	4 096	usual	176s	1 100s	2 353	1.47s	1 280s
	15	8 192	usual	1 030s	> 2 days	4 853	1.23s	59.0s
			This work	348s	3.47s	0		
Edwards	5	65 536	usual	12 300s	> 2 days	0	7 820s	> 2 days 20 200s
Edwards weights	5	65 536	This work	12 300s	40.8s			
Pathological	9	512	usual	0s	12.8s	255	0.01s	12.8s
			This work	< 0.01s	< 0.01s	0	< 0.01s	< 0.01s
	11	2 048	usual	0s	7 520s	1 023	23.0s	7 540s
	16	65 536	usual	0s	5.02s	0	0.13s	5.28s
			This work	38 100s	> 2 days	32 767	14 300s	> 2 days 52 600s
					195s	0		

First conclusion

New probabilistic algorithm for solving PoSSo

- Complexity $\tilde{O}(d^{\omega n} + nD^\omega)$ arithmetic operations
- Real impacts in practice **intractable** → 20k seconds

Deterministic computation of μ_{x_i} ?

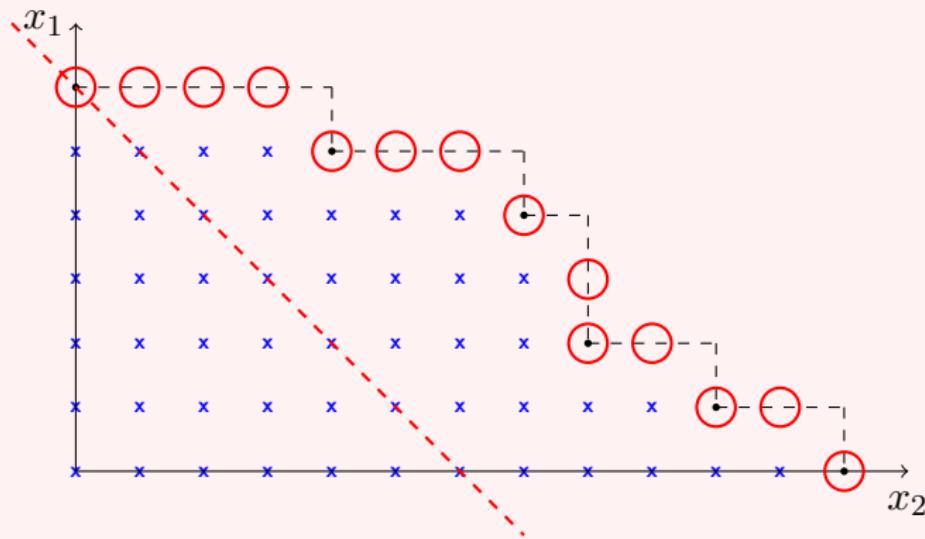


☞ All the NF of same degree terms are computed at the same time!

Computing $\mu_{x_1}, \dots, \mu_{x_n}$

Computing $\mu_{x_1}, \dots, \mu_{x_n} \Leftrightarrow$ computing $\text{NF}_{DRL}(\epsilon_i x_j)$ $i = 1, \dots, D$ and $j = 1, \dots, n$

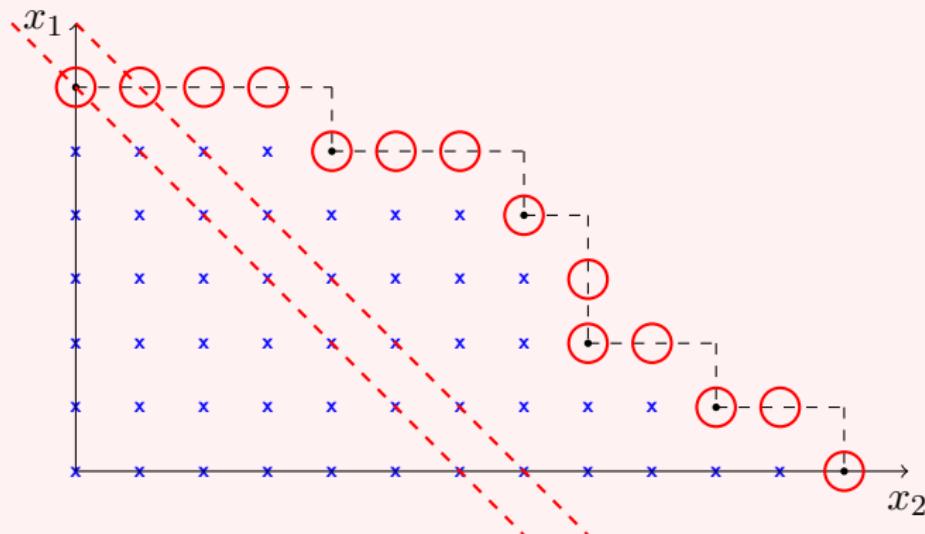
This work



Computing $\mu_{x_1}, \dots, \mu_{x_n}$

Computing $\mu_{x_1}, \dots, \mu_{x_n} \Leftrightarrow$ computing $\text{NF}_{DRL}(\epsilon_i x_j)$ $i = 1, \dots, D$ and $j = 1, \dots, n$

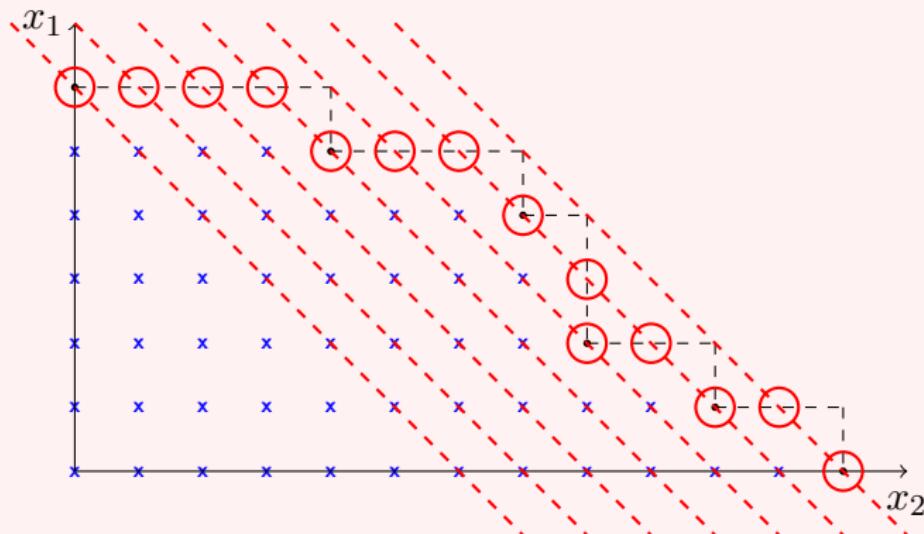
This work



Computing $\mu_{x_1}, \dots, \mu_{x_n}$

Computing $\mu_{x_1}, \dots, \mu_{x_n} \Leftrightarrow$ computing $\text{NF}_{DRL}(\epsilon_i x_j)$ $i = 1, \dots, D$ and $j = 1, \dots, n$

This work



Computing $\mu_{x_1}, \dots, \mu_{x_n}$ using fast linear algebra

Iterative algorithm: loop on the **degree** d

$t_\ell \in F$ $\deg(t_\ell) = d$	$t_j \in F$ $\deg(t_j) < d$	$\epsilon_i \in B$ Read NF
$t_j - \text{NF}(t_j)$ $\forall t_j \in F, \deg(t_j) < d$	$0 \ 0 \ \cdots \ 0$ $\vdots \ \vdots \ \ddots \ \vdots$ $0 \ 0 \ \cdots \ 0$	$1 \ \cdots \ 0$ $\vdots \ \ddots \ \vdots$ $0 \ \cdots \ 1$

Computing $\mu_{x_1}, \dots, \mu_{x_n}$ using fast linear algebra

Iterative algorithm: loop on the **degree** d

$t_\ell \in F$ $\deg(t_\ell) = d$	$t_j \in F$ $\deg(t_j) < d$	$\epsilon_i \in B$
$f_\ell \in \mathcal{I}, \text{LT}(f_\ell) = t_\ell$	$1 \star \cdots \star$	$\star \cdots \star \star \cdots \star$
$\forall t_\ell \in F, \deg(t_\ell) = d$	$0 1 \vdots \star \cdots \star$	$\star \cdots \star \star \cdots \star$
	$\vdots \text{T} \ddots \star$	$\vdots \text{A} \ddots \vdots \text{B} \ddots$
$t_j - \text{NF}(t_j)$	$0 0 \cdots 1$	$\star \cdots \star \star \cdots \star$
$\forall t_j \in F, \deg(t_j) < d$	$0 0 \cdots 0$	$1 \cdots 0 \star \cdots \star$
	$\vdots \vdots \ddots \vdots$	$\vdots \vdots \text{C} \vdots$
	$0 0 \cdots 0$	$0 \cdots 1 \star \cdots \star$

- If $t_\ell \in E(>_1)\mathcal{I}$ then $f_\ell = g$ with $g \in \mathcal{G}_{>_1}$ st $\text{LT}_{>_1}(g) = t_\ell$;
- Else $t_\ell \in F \setminus E(>_1)\mathcal{I} \Rightarrow t_\ell = x_k t_j$ and
 $f_\ell = x_k(t_j - \text{NF}_{>_1}(t_j)) = t_\ell + \sum_{i=1}^D \alpha_i x_k \epsilon_i$.

Computing $\mu_{x_1}, \dots, \mu_{x_n}$ using fast linear algebra

Iterative algorithm: loop on the **degree** d

$t_\ell \in F$ $\deg(t_\ell) = d$	$t_j \in F$ $\deg(t_j) < d$	$\epsilon_i \in B$ Read NF
$1 \ 0 \ \cdots \ 0$	$0 \ \cdots \ 0$	$\star \ \cdots \ \star$
$0 \ 1 \ \vdots$	$0 \ \cdots \ 0$	$\star \ \cdots \ \star$
$\vdots \ \ddots \ 0$	$\vdots \ \ddots$	$: \mathbf{T}^{-1}(\mathbf{B} - \mathbf{AC}) \quad \forall t_\ell \in F, \deg(t_\ell) = d$
$0 \ 0 \ \cdots \ 1$	$0 \ \cdots \ 0$	$\star \ \cdots \ \star$
$0 \ 0 \ \cdots \ 0$	$1 \ \cdots \ 0$	$\star \ \cdots \ \star$
$\vdots \ \vdots \ \ddots \ \vdots$	$\vdots \ \ddots$	$\mathbf{C} \quad \forall t_j \in F, \deg(t_j) < d$
$0 \ 0 \ \cdots \ 0$	$0 \ \cdots \ 1$	$\star \ \cdots \ \star$

Reduced Row
Echelon Form \rightsquigarrow

The normal forms of all the monomials of same degree can be computed simultaneously.

Computing $\mu_{x_1}, \dots, \mu_{x_n}$ using fast linear algebra

Size of M at most $(nD \times (n + 1)D)$.

Theorem

Given \mathcal{G}_{DRL} , the computation can be done in

$$O(d_{\max} n^{\omega} D^{\omega}) \text{ arithmetic operations}$$

where $d_{\max} = \max\{\deg(t) \mid t \in F\} = \max\{\deg(g) \mid g \in \mathcal{G}_{DRL}\}$.

Regular System

Let $S = \{f_1, \dots, f_n\}$ with $\deg(f_i) \leq d$ and (f_1, \dots, f_n) is a regular sequence. For the **DRL** ordering

- Macaulay's bound $\Rightarrow d_{\max} \leq n(d - 1) + 1$;
- Bézout's bound $\Rightarrow D \leq d^n$.

d fixed integer $\Rightarrow O(d_{\max} n^{\omega} D^{\omega}) = O(n^{\omega+1} D^{\omega}) = O(\log_2(D)^{\omega+1} D^{\omega})$.

Final conclusion

- New probabilistic algo for solving PoSSo with complexity $\tilde{O}(d^{\omega n} + nD^\omega)$ arithmetic operations
- Sub-cubic deterministic algo for the computations of the μ_{x_i} 's \rightsquigarrow triangular sets (see Louise's PhD, extended version)

Thank you!